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ABSTRACT

Circlip pliers (1) have two pliers limbs (2), which are formed for gripping, and two pliers tips (5), and insertion tips (6) for introduction into actuating eyelets (7) of a circlip (8) being provided on the pliers tips (5). The insertion tips are rooted in a contact surface (9) of the pliers tips (5), wherein, in the unactuated state of the pliers, longitudinal axes (x-x) of the insertion tips (6) enclose an acute angle (α) with one another, and the planar contact surface (9) likewise forms an acute angle (β) with a perpendicular (y-y) to such a longitudinal axis (x-x), and wherein the contact surfaces (9) of the pliers tips (5) form an obtuse angle with one another.